# MICROPROCESSORS AND MICROCONTROLLERS <br> LAB 

## DA-3

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Aim:
i.) Write an 8051 ALP program to generate a pulse waveform with given duty cycle using timer.
ii.) Write an 8051 ALP program to generate a pulse waveform with given time-period using timer. $T=x x$ ms (Reg: 22BCE29xx)
iii.) Write an 8051 ALP to get the radius of sphere ( 8 -bit) from port P1. Calculate the volume (V) and total surface area (A). Send the following messages through UART1. "Volume of the sphere is $V$ " "Total surface area is $A$ "

## Procedure:

i.) Start up the Keil $\mu$ Vision Software.
ii.) Create new $\mu$ Vision project at required directory.
iii.) Set the device as 8051 microcontroller (AT89C51).
iv.) Create new item at Source Group 1 in Target 1.
v.) Set the file type as ASM file.
vi.) Continue writing the code for the ALP.

# vii.)Translate and build the file. viii.) Start debug session, and run code line by line to get output <br> ix.) Check output at the memory location set, in memory 1. 

## Algorithm:

## a.) To generate a pulse waveform with given duty cycle using timer:-

1. Set up Timer 0 in mode 1 with an external clock source.
2. Clear Timer 0 flag.
3. Enter an infinite loop: a. Set P2.3 high. b. Start Timer 0 with a delay determined by ON_DELAY subroutine. c. Clear P2.3. d. Start Timer 0 with a delay determined by OFF_DELAY subroutine.
ON_DELAY Subroutine:
4. Load Timer 0 with a delay for the LED ON time.
5. Start Timer 0 and wait until it overflows (TF0 flag is set).
6. Stop Timer 0 and clear its flag.

OFF_DELAY Subroutine:

1. Load Timer 0 with a delay for the LED OFF time.
2. Start Timer 0 and wait until it overflows (TF0 flag is set).
3. Stop Timer 0 and clear its flag.

## b.) to generate a pulse waveform with given time-period using timer. T = xx <br> ms (Reg: 22BCE29xx):-

1. Set up Timer 0 in mode 1
2. Use an external clock source.
3. Clear Timer 0 flag.
4. Enter an infinite loop: a. Set P2.3 high. b. Start Timer 0 with a delay determined by ON_DELAY subroutine. c. Clear P2.3. d. Start Timer 0 with a delay determined by OFF_DELAY subroutine.
ON_DELAY Subroutine:
5. Load Timer 0 with a delay for the LED ON time.
6. Start Timer 0 and wait until it overflows (TF0 flag is set).
7. Stop Timer 0 and clear its flag.

OFF_DELAY Subroutine:
8. Load Timer 0 with a delay for the LED OFF time.
9. Start Timer 0 and wait until it overflows (TFO flag is set).
10. Stop Timer 0 and clear its flag.

## C.) to get the radius of sphere ( 8 -bit) from port P1.

 Calculate the volume ( V ) and total surface area (A):-1. Initialization:

- Move the value of Port 1 (P1) to Register 0 (R0).
- Copy R0 to Accumulator (A) and Register B.
- Initialize Register 1 (R1) for storing results.

2. Calculate Surface Area:

- Square the radius ( $A^{*} B$ ) and multiply by a constant to get $4 \times 8 \times 824 \times \pi \times r 2$.
- Convert the result to ASCII and store it in memory.

3. Send Surface Area via Serial Port:

- Iterate through data array DAT0 and send data to the serial port.

4. Calculate Volume:

- Decrement the ASCII counter (R1) and recalculate the radius cubed.
- Multiply to get $43 \times 8 \times 8334 \times \pi \times r$.
- Convert the result to ASCII and store it in memory.

5. Send Volume via Serial Port:

- Iterate through data array DAT1 and send data to the serial port.

6. Data Definitions:

- Define data strings for surface area and volume messages.

7. End of Program.

## Code:

## a.) To generate a pulse waveform with given duty cycle using timer:-

```
MOV IMOD, #O1H
CLR IFO
HERE:
SETB P2.3
ACALI ON_DELAY
CLR P2.3
ACAIL OFF_DELAY
SJMP HERE
ON DELAY:
MOV IHO, #OEFH
MOV ILO, #OOH
SEIB IRO
TNB TFO, F
    CLR IRO
    CLR IFO
    REI
    OHE_DELAY=
    MOV IHO, #OEBH
    MOV ILO, #OE2H
    SETB IRO
        JNB IFO, F
            CLR IRO
            CLR IFO
            RET
                END
```

b.) to generate a pulse waveform with given time-period using timer. $\mathrm{T}=\mathrm{xx} \mathrm{ms}$ (Reg: 22BCE29xx):-

|  | 1 | MOV TMOD, \#01H |
| :---: | :---: | :---: |
|  | 2 | CLR TEO |
|  | 3 |  |
|  | 4 | HERE: |
|  | 5 | SETB P2.3 |
|  | 6 | ACALL ON_DELAY |
|  | 7 | CLR P2.3 |
|  | 8 | ACALL OFF_DELAY |
|  | 9 | SJMP HERE |
|  | 10 |  |
|  | 11 | ON_DELAY: |
|  | 12 | MOV THO,\#OEFH |
|  | 13 | MOV TLO, \#00H |
|  | 14 | SETB TRO |
|  | 15 | JNB TEO, \$ |
|  | 16 | CLR TR0 |
|  | 17 | CLR TFO |
|  | 18 | RET |
|  | 19 |  |
|  | 20 | OEF_DELAY: |
|  | 21 | MOV THO, \#OESH |
| V | 22 | MOV TLO, \#OBAH |
|  | 23 | SEIB TRO |
|  | 24 | JNB TEO, ${ }^{\text {F }}$ |
|  | 25 | CLR TRO |
|  | 26 | CLR TFO |
|  | 27 | RET |
|  | 28 |  |
|  | 29 | END |
|  | 30 |  |

## C.)

to get the radius of sphere (8-bit) from port P1. Calculate the volume (V) and total surface area (A):-


| 〉 | 29 | DJNZ R3,AGAIN2 |
| :---: | :---: | :---: |
|  | 30 |  |
|  | 31 | AGAIN: MOV A,R1 |
|  | 32 | SUBB A, 401 H |
|  | 33 | MOV R1, A |
|  | 34 | MOV SBUF,@R1 |
|  | 35 | CHECK_I12: JNB TI,CHECK_T12 |
|  | 36 | CLR TI |
|  | 37 | MOV A, R1 |
|  | 38 | CJNE A, $\ddagger 20$, AGAIN |
|  | 39 |  |
|  | 40 | MOV A, RO |
|  | 41 | MOV B, R0 |
|  | 42 | MUL AB |
|  | 43 | MOV B, R0 |
|  | 44 | MUL AB |
|  | 45 | MOV B, \#04H |
|  | 46 | MUL AB |
|  | 47 | MOV R1, $\ddagger 20 \mathrm{H}$ |
|  | 48 |  |
|  | 49 | CONVERI_TO_ASCII2: |
|  | 50 | MOV B, \%10D |
|  | 51 | DIV AB |
|  | 52 | MOV $\mathrm{A}, \mathrm{B}$ |
|  | 53 | ADD A, \#30H |
|  | 54 | MOV @R1, A |
|  | 55 | INC R1 |
|  | 56 | MOV A, R7 |


| 57 | CJNE A, $\ddagger 0$, CONVERI_TO_ASCII2 |
| :---: | :---: |
| 58 |  |
| 59 | MOV R3, \#26D |
| 60 | MOV R2, \#0 |
| 61 | MOV DPTR, \#DAT1 |
| 62 | AGAIN3:MOV A,R2 |
| 63 | MOVC A, @A +DPTR |
| 64 | MOV SBUF, A |
| 65 | CHECK_III:JNB II, CHECK_TII |
| 66 | CLR TI |
| 67 | INC R2 |
| 68 | DJNZ R3, AGAIN3 |
| 69 |  |
| 70 | AGAIN4:MOV A,R1 |
| 71 | SUBB A, \#01H |
| 72 | MOV R1, A |
| 73 | MOV SBUF, @RI |
| 74 | CHECK_II3: JNB II, CHECK_TI3 |
| 75 | CLR TI |
| 76 | MOV A, R1 |
| 77 | CJNE A, $420 \mathrm{H}, \mathrm{AGAIN} 4$ |
| 78 |  |
| 79 | DAIO: DB "TOTAL SURFACE AREA IS", 0 |
| 80 |  |
| 81 | DAT1: DB "VOLUME OF THE SPHERE IS", 0 |
| 82 |  |
| 83 | END |

## Output:

## a.)


b.)


## C.)

## UART \#1

TOTAL SURFACE AREA IS 14

